

FlexMix Version 2: Finite Mixtures with Concomitant Variables and Varying and Constant Parameters

Bettina Grün

Friedrich Leisch

Johannes Kepler Universität Linz Ludwig-Maximilians-Universität München

Abstract

This article is a (slightly) modified version of Grün and Leisch (2008b), published in the *Journal of Statistical Software*.

flexmix provides infrastructure for flexible fitting of finite mixture models in R using the expectation-maximization (EM) algorithm or one of its variants. The functionality of the package was enhanced. Now concomitant variable models as well as varying and constant parameters for the component specific generalized linear regression models can be fitted. The application of the package is demonstrated on several examples, the implementation described and examples given to illustrate how new drivers for the component specific models and the concomitant variable models can be defined.

Keywords: R, finite mixture models, generalized linear models, concomitant variables.

1. Introduction

Finite mixture models are a popular technique for modelling unobserved heterogeneity or to approximate general distribution functions in a semi-parametric way. They are used in a lot of different areas such as astronomy, biology, economics, marketing or medicine. An overview on mixture models is given in Everitt and Hand (1981), Titterington, Smith, and Makov (1985), McLachlan and Basford (1988), Böhning (1999), McLachlan and Peel (2000) and Frühwirth-Schnatter (2006).

Version 1 of R package **flexmix** was introduced in Leisch (2004b). The main design principles of the package are extensibility and fast prototyping for new types of mixture models. It uses S4 classes and methods (Chambers 1998) as implemented in the R package **methods** and exploits advanced features of R such as lexical scoping (Gentleman and Ihaka 2000). The package implements a framework for maximum likelihood estimation with the expectation-maximization (EM) algorithm (Dempster, Laird, and Rubin 1977). The main focus is on finite mixtures of regression models and it allows for multiple independent responses and repeated measurements. The EM algorithm can be controlled through arguments such as the maximum number of iterations or a minimum improvement in the likelihood to continue.

Newly introduced features in the current package version are concomitant variable models (Dayton and Macready 1988) and varying and constant parameters in the component specific regressions. Varying parameters follow a finite mixture, i.e., several groups exist in the population which have different parameters. Constant parameters are fixed for the whole

population. This model is similar to mixed-effects models (Pinheiro and Bates 2000). The main difference is that in this application the distribution of the varying parameters is unknown and has to be estimated. Thus the model is actually closer to the varying-coefficients modelling framework (Hastie and Tibshirani 1993), using convex combinations of discrete points as functional form for the varying coefficients.

The extension to constant and varying parameters allows for example to fit varying intercept models as given in Follmann and Lambert (1989) and Aitkin (1999a). These models are frequently applied to account for overdispersion in the data where the components follow either a binomial or Poisson distribution. The model was also extended to include nested varying parameters, i.e. this allows to have groups of components with the same parameters (Grün and Leisch 2006; Grün 2006).

In Section 2 the extended model class is presented together with the parameter estimation using the EM algorithm. In Section 3 examples are given to demonstrate how the new functionality can be used. An overview on the implementational details is given in Section 4. The new model drivers are presented and changes made to improve the flexibility of the software and to enable the implementation of the new features are discussed. Examples for writing new drivers for the component specific models and the concomitant variable models are given in Section 5. This paper gives a short overview on finite mixtures and the package in order to be self-contained. A more detailed introduction to finite mixtures and the package **flexmix** can be found in Leisch (2004b).

All computations and graphics in this paper have been done with **flexmix** version 2.2-10 and R version 2.11.1 using Sweave (Leisch 2002). The newest release version of **flexmix** is always available from the Comprehensive R Archive Network at <http://CRAN.R-project.org/package=flexmix>. An up-to-date version of this paper is contained in the package as a vignette, giving full access to the R code behind all examples shown below. See `help("vignette")` or Leisch (2003) for details on handling package vignettes.

2. Model specification and estimation

A general model class of finite mixtures of regression models is considered in the following. The mixture is assumed to consist of K components where each component follows a parametric distribution. Each component has a weight assigned which indicates the a-priori probability for an observation to come from this component and the mixture distribution is given by the weighted sum over the K components. If the weights depend on further variables, these are referred to as concomitant variables.

In marketing choice behaviour is often modelled in dependence of marketing mix variables such as price, promotion and display. Under the assumption that groups of respondents with different price, promotion and display elasticities exist mixtures of regressions are fitted to model consumer heterogeneity and segment the market. Socio-demographic variables such as age and gender have often been shown to be related to the different market segments even though they generally do not perform well when used to a-priori segment the market. The relationships between the behavioural and the socio-demographic variables is then modelled through concomitant variable models where the group sizes (i.e. the weights of the mixture) depend on the socio-demographic variables.

The model class is given by

$$\begin{aligned} h(y|x, w, \psi) &= \sum_{k=1}^K \pi_k(w, \alpha) f_k(y|x, \theta_k) \\ &= \sum_{k=1}^K \pi_k(w, \alpha) \prod_{d=1}^D f_{kd}(y_d|x_d, \theta_{kd}), \end{aligned}$$

where ψ denotes the vector of all parameters for the mixture density $h()$ and is given by $(\alpha, (\theta_k)_{k=1, \dots, K})$. y denotes the response, x the predictor and w the concomitant variables. f_k is the component specific density function. Multivariate variables y are assumed to be dividable into D subsets where the component densities are independent between the subsets, i.e. the component density f_k is given by a product over D densities which are defined for the subset variables y_d and x_d for $d = 1, \dots, D$. The component specific parameters are given by $\theta_k = (\theta_{kd})_{d=1, \dots, D}$. Under the assumption that N observations are available the dimensions of the variables are given by $y = (y_d)_{d=1, \dots, D} \in \mathbb{R}^{N \times \sum_{d=1}^D k_{yd}}$, $x = (x_d)_{d=1, \dots, D} \in \mathbb{R}^{N \times \sum_{d=1}^D k_{xd}}$ for all $d = 1, \dots, D$ and $w \in \mathbb{R}^{N \times k_w}$. In this notation k_{yd} denotes the dimension of the d^{th} response, k_{xd} the dimension of the d^{th} predictors and k_w the dimension of the concomitant variables. For mixtures of GLMs each of the d responses will in general be univariate, i.e. multivariate responses will be conditionally independent given the segment memberships.

For the component weights π_k it holds $\forall w$ that

$$\sum_{k=1}^K \pi_k(w, \alpha) = 1 \quad \text{and} \quad \pi_k(w, \alpha) > 0, \forall k, \quad (1)$$

where α are the parameters of the concomitant variable model.

For the moment focus is given to finite mixtures where the component specific densities are from the same parametric family, i.e. $f_{kd} \equiv f_d$ for notational simplicity. If f_d is from the exponential family of distributions and for each component a generalized linear model is fitted (GLMs; McCullagh and Nelder 1989) these models are also called GLIMMIX models (Wedel and DeSarbo 1995). In this case the component specific parameters are given by $\theta_{kd} = (\beta'_{kd}, \phi_{kd})$ where β_{kd} are the regression coefficients and ϕ_{kd} is the dispersion parameter. The component specific parameters θ_{kd} are either restricted to be equal over all components, to vary between groups of components or to vary between all components. The varying between groups is referred to as varying parameters with one level of nesting. A disjoint partition K_c , $c = 1, \dots, C$ of the set $\tilde{K} := \{1, \dots, K\}$ is defined for the regression coefficients. C is the number of groups of the regression coefficients at the nesting level. The regression coefficients are accordingly split into three groups:

$$\beta_{kd} = (\beta'_{1d}, \beta'_{2, c(k)d}, \beta'_{3, kd})',$$

where $c(k) = \{c = 1, \dots, C : k \in K_c\}$.

Similar a disjoint partition K_v , $v = 1, \dots, V$, of \tilde{K} can be defined for the dispersion parameters if nested varying parameters are present. V denotes the number of groups of the dispersion

parameters at the nesting level. This gives:

$$\phi_{kd} = \begin{cases} \phi_d & \text{for constant parameters} \\ \phi_{kd} & \text{for varying parameters} \\ \phi_{v(k)d} & \text{for nested varying parameters} \end{cases}$$

where $v(k) = \{v = 1, \dots, V : k \in K_v\}$. The nesting structure of the component specific parameters is also described in Grün and Leisch (2006).

Different concomitant variable models are possible to determine the component weights (Dayton and Macready 1988). The mapping function only has to fulfill condition (1). In the following a multinomial logit model is assumed for the π_k given by

$$\pi_k(w, \alpha) = \frac{e^{w' \alpha_k}}{\sum_{u=1}^K e^{w' \alpha_u}} \quad \forall k,$$

with $\alpha = (\alpha'_k)_{k=1, \dots, K}'$ and $\alpha_1 \equiv 0$.

2.1. Parameter estimation

The EM algorithm (Dempster *et al.* 1977) is the most common method for maximum likelihood estimation of finite mixture models where the number of components K is fixed. The EM algorithm applies a missing data augmentation scheme. It is assumed that a latent variable $z_n \in \{0, 1\}^K$ exists for each observation n which indicates the component membership, i.e. z_{nk} equals 1 if observation n comes from component k and 0 otherwise. Furthermore it holds that $\sum_{k=1}^K z_{nk} = 1$ for all n . In the EM algorithm these unobserved component memberships z_{nk} of the observations are treated as missing values and the data is augmented by estimates of the component membership, i.e. the estimated a-posteriori probabilities \hat{p}_{nk} . For a sample of N observations $\{(y_1, x_1, w_1), \dots, (y_N, x_N, w_N)\}$ the EM algorithm is given by:

E-step: Given the current parameter estimates $\psi^{(i)}$ in the i -th iteration, replace the missing data z_{nk} by the estimated a-posteriori probabilities

$$\hat{p}_{nk} = \frac{\pi_k(w_n, \alpha^{(i)}) f(y_n | x_n, \theta_k^{(i)})}{\sum_{u=1}^K \pi_u(w_n, \alpha^{(i)}) f(y_n | x_n, \theta_u^{(i)})}.$$

M-step: Given the estimates for the a-posteriori probabilities \hat{p}_{nk} (which are functions of $\psi^{(i)}$), obtain new estimates $\psi^{(i+1)}$ of the parameters by maximizing

$$Q(\psi^{(i+1)} | \psi^{(i)}) = Q_1(\theta^{(i+1)} | \psi^{(i)}) + Q_2(\alpha^{(i+1)} | \psi^{(i)}),$$

where

$$Q_1(\theta^{(i+1)} | \psi^{(i)}) = \sum_{n=1}^N \sum_{k=1}^K \hat{p}_{nk} \log(f(y_n | x_n, \theta_k^{(i+1)}))$$

and

$$Q_2(\alpha^{(i+1)} | \psi^{(i)}) = \sum_{n=1}^N \sum_{k=1}^K \hat{p}_{nk} \log(\pi_k(w_n, \alpha^{(i+1)})).$$

Q_1 and Q_2 can be maximized separately. The maximization of Q_1 gives new estimates $\theta^{(i+1)}$ and the maximization of Q_2 gives $\alpha^{(i+1)}$. Q_1 is maximized separately for each $d = 1, \dots, D$ using weighted ML estimation of GLMs and Q_2 using weighted ML estimation of multinomial logit models.

Different variants of the EM algorithm exist such as the stochastic EM (SEM; [Diebolt and Ip 1996](#)) or the classification EM (CEM; [Celeux and Govaert 1992](#)). These two variants are also implemented in package **flexmix**. For both variants an additional step is made between the expectation and maximization steps. This step uses the estimated a-posteriori probabilities and assigns each observation to only one component, i.e. classifies it into one component. For SEM this assignment is determined in a stochastic way while it is a deterministic assignment for CEM. For the SEM algorithm the additional step is given by:

S-step: Given the a-posteriori probabilities draw

$$\hat{z}_n \sim \text{Mult}((\hat{p}_{nk})_{k=1,\dots,K}, 1)$$

where $\text{Mult}(\theta, T)$ denotes the multinomial distribution with success probabilities θ and number of trials T .

Afterwards, the \hat{z}_{nk} are used instead of the \hat{p}_{nk} in the M-step. For the CEM the additional step is given by:

C-step: Given the a-posteriori probabilities define

$$\hat{z}_{nk} = \begin{cases} 1 & \text{if } k = \min\{l : \hat{p}_{nl} \geq \hat{p}_{nk} \forall k = 1, \dots, K\} \\ 0 & \text{otherwise.} \end{cases}$$

Please note that in this step the observation is assigned to the component with the smallest index if the same maximum a-posteriori probability is observed for several components.

Both of these variants have been proposed to improve the performance of the EM algorithm, because the ordinary EM algorithm tends to converge rather slowly and only to a local optimum. The convergence behavior can be expected to be better for the CEM than ordinary EM algorithm, while SEM can escape convergence to a local optimum. However, the CEM algorithm does not give ML estimates because it maximizes the complete likelihood. For SEM good approximations of the ML estimator are obtained if the parameters where the maximum likelihood was encountered are used as estimates. Another possibility for determining parameter estimates from the SEM algorithm could be the mean after discarding a suitable number of burn-ins. An implementational advantage of both variants is that no weighted maximization is necessary in the M-step.

It has been shown that the values of the likelihood are monotonically increased during the EM algorithm. On the one hand this ensures the convergence of the EM algorithm if the likelihood is bounded, but on the other hand only the detection of a local maximum can be guaranteed. Therefore, it is recommended to repeat the EM algorithm with different initializations and choose as final solution the one with the maximum likelihood. Different initialization strategies for the EM algorithm have been proposed, as its convergence to the optimal solution depends on the initialization ([Biernacki, Celeux, and Govaert 2003](#); [Karlis and Xekalaki 2003](#)). Proposed strategies are for example to first make several runs of the

SEM or CEM algorithm with different random initializations and then start the EM at the best solution encountered.

The component specific parameter estimates can be determined separately for each $d = 1, \dots, D$. For simplicity of presentation the following description assumes $D = 1$. If all parameter estimates vary between the component distributions they can be determined separately for each component in the M-step. However, if also constant or nested varying parameters are specified, the component specific estimation problems are not independent from each other any more. Parameters have to be estimated which occur in several or all components and hence, the parameters of the different components have to be determined simultaneously for all components. The estimation problem for all component specific parameters is then obtained by replicating the vector of observations $y = (y_n)_{n=1, \dots, N}$ K times and defining the covariate matrix $X = (X_{\text{constant}}, X_{\text{nested}}, X_{\text{varying}})$ by

$$\begin{aligned} X_{\text{constant}} &= \mathbf{1}_K \otimes (x'_{1,n})_{n=1, \dots, N} \\ X_{\text{nested}} &= \mathbf{J} \odot (x'_{2,n})_{n=1, \dots, N} \\ X_{\text{varying}} &= \mathbf{I}_K \otimes (x'_{3,n})_{n=1, \dots, N}, \end{aligned}$$

where $\mathbf{1}_K$ is a vector of 1s of length K , \mathbf{J} is the incidence matrix for each component $k = 1, \dots, K$ and each nesting group $c \in C$ and hence is of dimension $K \times |C|$, and \mathbf{I}_K is the identity matrix of dimension $K \times K$. \otimes denotes the Kronecker product and \odot the Khatri-Rao product (i.e., the column-wise Kronecker product). $x_{m,n}$ are the covariates of the corresponding coefficients $\beta_{m,\cdot}$ for $m = 1, 2, 3$. Please note that the weights used for the estimation are the a-posteriori probabilities which are stacked for all components, i.e. a vector of length NK is obtained.

Due to the replication of data in the case of constant or nested varying parameters the amount of memory needed for fitting the mixture model to large datasets is substantially increased and it might be easier to fit only varying coefficients to these datasets. To overcome this problem it could be considered to implement special data structures in order to avoid storing the same data multiple times for large datasets.

Before each M-step the average component sizes (over the given data points) are checked and components which are smaller than a given (relative) minimum size are omitted in order to avoid too small components where fitting problems might arise. This strategy has already been recommended for the SEM algorithm (Celeux and Diebolt 1988) because it allows to determine the suitable number of components in an automatic way given that the a-priori specified number of components is large enough. This recommendation is based on the assumption that the redundant components will be omitted during the estimation process if the algorithm is started with too many components. If omission of small components is not desired the minimum size required can be set to zero. All components will be then retained throughout the EM algorithm and a mixture with the number of components specified in the initialization will be returned. The algorithm is stopped if the relative change in the log-likelihood is smaller than a pre-specified ϵ or the maximum number of iterations is reached.

For model selection different information criteria are available: AIC, BIC and ICL (Integrated Complete Likelihood; Biernacki, Celeux, and Govaert 2000). They are of the form twice the negative loglikelihood plus number of parameters times k where $k = 2$ for the AIC and k equals the logarithm of the number of observations for the BIC. The ICL is the same as the BIC except that the complete likelihood (where the missing class memberships are replaced by

the assignments induced by the maximum a-posteriori probabilities) instead of the likelihood is used.

3. Using the new functionality

In the following model fitting and model selection in R is illustrated on several examples including mixtures of Gaussian, binomial and Poisson regression models, see also Grün (2006) and Grün and Leisch (2007).

More examples for mixtures of GLMs are provided as part of the software package through a collection of artificial and real world datasets, most of which have been previously used in the literature (see references in the online help pages). Each dataset can be loaded to R with `data("name")` and the fitting of the proposed models can be replayed using `example("name")`. Further details on these examples are given in a user guide which can be accessed using `vignette("regression-examples", package="flexmix")` from within R.

3.1. Artificial example

In the following the artificial dataset `NPreg` is used which has already been used in Leisch (2004b) to illustrate the application of package `flexmix`. The data comes from two latent classes of size 100 each and for each of the classes the data is drawn with respect to the following structure:

$$\begin{aligned}\text{Class~1: } & yn = 5x + \epsilon \\ \text{Class~2: } & yn = 15 + 10x - x^2 + \epsilon\end{aligned}$$

with $\epsilon \sim N(0, 9)$, see the left panel of Figure~1. The dataset `NPreg` also includes a response `yp` which is given by a generalized linear model following a Poisson distribution and using the logarithm as link function. The parameters of the mean are given for the two classes by:

$$\begin{aligned}\text{Class~1: } & \mu_1 = 2 - 0.2x \\ \text{Class~2: } & \mu_2 = 1 + 0.1x.\end{aligned}$$

This signifies that given x the response yp in group k follows a Poisson distribution with mean e^{μ_k} , see the right panel of Figure~1.

This model can be fitted in R using the commands:

```
R> set.seed(1802)
R> library("flexmix")
R> data("NPreg")
R> Model_n <- FLXMRglm(yn ~ . + I(x^2))
R> Model_p <- FLXMRglm(yp ~ ., family = "poisson")
R> m1 <- flexmix(. ~ x, data = NPreg, k = 2, model = list(Model_n, Model_p),
+   control = list(verbose = 10))
```

```
Classification: weighted
 10 Log-likelihood : -1044.7688
 11 Log-likelihood : -1044.7678
converged
```

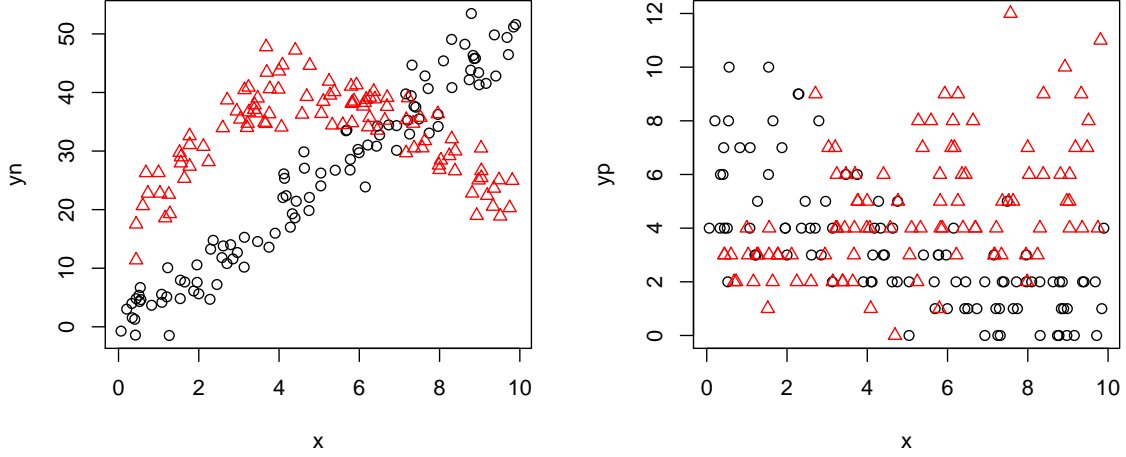



Figure 1: Standard regression example (left) and Poisson regression (right).

If the dimensions are independent the component specific model for multivariate observations can be specified as a list of models for each dimension.

The estimation can be controlled with the `control` argument which is specified with an object of class `"FLXcontrol"`. For convenience also a named list can be provided which is used to construct and set the respective slots of the `"FLXcontrol"` object. Elements of the control object are `classify` to select ordinary EM, CEM or SEM, `minprior` for the minimum relative size of components, `iter.max` for the maximum number of iterations and `verbose` for monitoring. If `verbose` is a positive integer the log-likelihood is reported every `verbose` iterations and at convergence together with the number of iterations made. The default is to not report any log-likelihood information during the fitting process.

The estimated model `m1` is of class `"flexmix"` and the result of the default plot method for this class is given in Figure~2. This plot method uses package `lattice` (Sarkar 2008) and the usual parameters can be specified to alter the plot, e.g.~the argument `layout` determines the arrangement of the panels. The returned object is of class `"trellis"` and the plotting can also be influenced by the arguments of its `show` method.

The default plot prints rootograms (i.e., a histogram of the square root of counts) of the a-posteriori probabilities of each observation separately for each component. For each component the observations with a-posteriori probabilities less than a pre-specified ϵ (default is 10^{-4}) for this component are omitted in order to avoid that the bar at zero dominates the plot (Leisch 2004a). Please note that the labels of the y-axis report the number of observations in each bar, i.e.~the squared values used for the rootograms.

More detailed information on the estimated parameters with respect to standard deviations and significance tests can be obtained with function `refit()`. This function determines the variance-covariance matrix of the estimated parameters by using the inverted negative Hesse matrix as computed by the general purpose optimizer `optim()` on the full likelihood of the model. `optim()` is initialized in the solution obtained with the EM algorithm. For mixtures

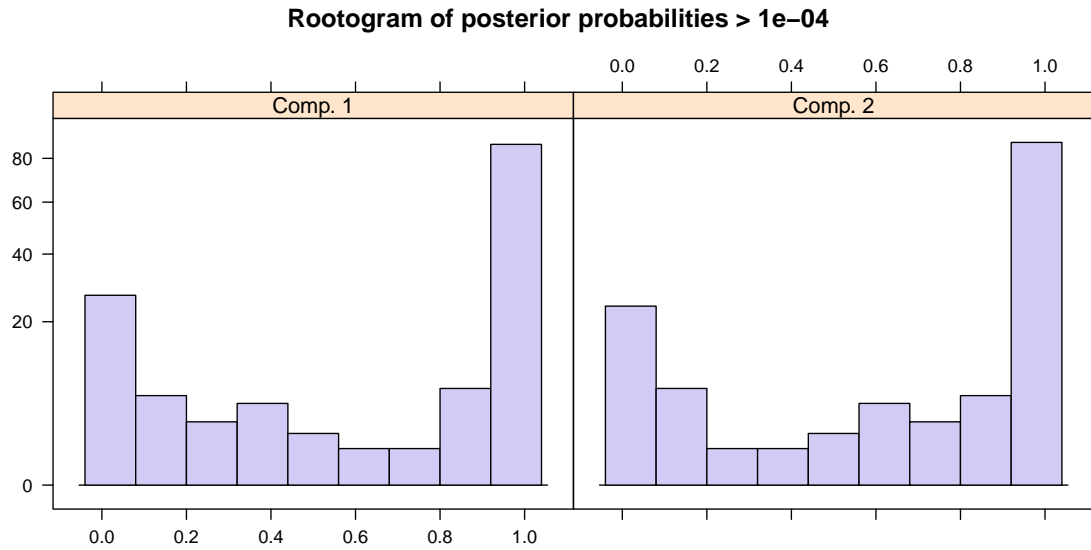


Figure 2: The plot method for "flexmix" objects, here obtained by `plot(m1)`, shows rootograms of the posterior class probabilities.

of GLMs we also implemented the gradient, which speeds up convergence and gives more precise estimates of the Hessian.

Naturally, function `refit()` will also work for models which have been determined by applying some model selection strategy depending on the data (AIC, BIC, ...). The same caution is necessary as when using `summary()` on standard linear models selected using `step()`: The p-values shown are not correct because they have not been adjusted for the fact that the same data are used to select the model and compute the p-values. So use them only in an exploratory manner in this context, see also [Harrell \(2001\)](#) for more details on the general problem.

The returned object can be inspected using `summary()` with arguments `which` to specify if information for the component model or the concomitant variable model should be shown and `model` to indicate for which dimension of the component models this should be done. Selecting `model=1` gives the parameter estimates for the dimension where the response variable follows a Gaussian distribution.

```
R> m1.refit <- refit(m1)
R> summary(m1.refit, which = "model", model = 1)

$Comp.1
      Estimate Std. Error z value Pr(>|z|)
(Intercept) 14.58965    1.24635  11.706 < 2.2e-16 ***
x             9.91572    0.55294  17.933 < 2.2e-16 ***
I(x^2)       -0.97578    0.05201 -18.762 < 2.2e-16 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

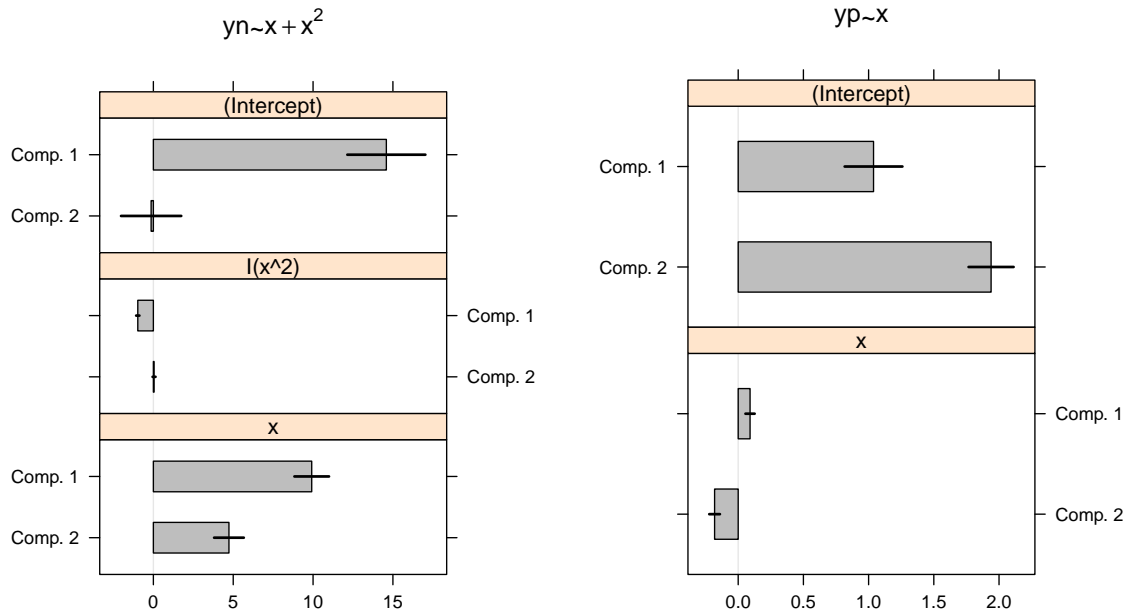


Figure 3: The default plot for refitted "flexmix" objects, here obtained by `plot(refit(m1), model = 1)` and `plot(refit(m1), model = 2)`, shows the coefficient estimates and their confidence intervals.

\$Comp.2

	Estimate	Std. Error	z value	Pr(> z)
(Intercept)	-0.140549	0.961868	-0.1461	0.8838
x	4.732610	0.474428	9.9754	<2e-16 ***
I(x^2)	0.042722	0.046890	0.9111	0.3622

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

The default plot method for the refitted "flexmix" object depicts the estimated coefficients with corresponding confidence intervals and is given in Figure~3. It can be seen that for the first model the confidence intervals of the coefficients of the intercept and the quadratic term of x overlap with zero.

A model where these coefficients are set to zero can be estimated with the model driver function `FLXMRglmfix()` and the following commands for specifying the nesting structure. The argument `nested` needs input for the number of components in each group (given by `k`) and the formula which determines the model matrix for the nesting (given by `formula`). This information can be provided in a named list.

For the restricted model the element `k` is a vector with two 1s because each of the components has different parameters. The formulas specifying the model matrices of these coefficients are $\sim 1 + I(x^2)$ for an intercept and a quadratic term of x for component 1 and ~ 0 for no additional coefficients for component 2. The EM algorithm is initialized in the previously fitted model by passing the posterior probabilities in the argument `cluster`.

```
R> Model_n2 <- FLXMRglmfix(yn ~ . + 0, nested = list(k = c(1, 1),
```

```
+   formula = c(~ 1 + I(x^2), ~ 0)))
R> m2 <- flexmix(. ~ x, data = NPreg, cluster = posterior(m1),
+   model = list(Model_n2, Model_p))
R> m2
```

Call:

```
flexmix(formula = . ~ x, data = NPreg, cluster = posterior(m1),
  model = list(Model_n2, Model_p))
```

Cluster sizes:

```
1    2
96 104
```

convergence after 3 iterations

Model selection based on the BIC would suggest the smaller model which also corresponds to the true underlying model.

```
R> c(BIC(m1), BIC(m2))
```

```
[1] 2158.414 2149.956
```

3.2. Beta-blockers dataset

The dataset is analyzed in [Aitkin \(1999a,b\)](#) using a finite mixture of binomial regression models. Furthermore, it is described in [McLachlan and Peel \(2000, p.~165\)](#). The dataset is from a 22-center clinical trial of beta-blockers for reducing mortality after myocardial infarction. A two-level model is assumed to represent the data, where centers are at the upper level and patients at the lower level. The data is illustrated in [Figure~4](#).

First, the center information is ignored and a binomial logit regression model with treatment as covariate is fitted using `glm`, i.e. $K = 1$ and it is assumed that the different centers are comparable:

```
R> data("betablocker")
R> betaGlm <- glm(cbind(Deaths, Total - Deaths) ~ Treatment,
+   family = "binomial", data = betablocker)
R> betaGlm
```

Call: `glm(formula = cbind(Deaths, Total - Deaths) ~ Treatment, family = "binomial",`

Coefficients:

```
(Intercept) TreatmentTreated
-2.1971      -0.2574
```

Degrees of Freedom: 43 Total (i.e. Null); 42 Residual

Null Deviance: 333

Residual Deviance: 305.8 AIC: 527.2

The residual deviance suggests that overdispersion is present in the data. In the next step the intercept is allowed to follow a mixture distribution given the centers. This signifies that the component membership is fixed for each center. This grouping is specified in R by adding `| Center` to the formula similar to the notation used in `nlme` (Pinheiro and Bates 2000). Under the assumption of homogeneity within centers identifiability of the model class can be ensured as induced by the sufficient conditions for identifiability given in Follmann and Lambert (1991) for binomial logit models with varying intercepts and Grün and Leisch (2008a) for multinomial logit models with varying and constant parameters. In order to determine the suitable number of components, the mixture is fitted with different numbers of components.

```
R> betaMixFix <- stepFlexmix(cbind(Deaths, Total - Deaths) ~ 1 | Center,
+   model = FLXMRglmfix(family = "binomial", fixed = ~ Treatment),
+   k = 2:4, nrep = 5, data = betablocker)
```

```
2 : * * * * *
3 : * * * * *
4 : * * * * *
```

The returned object is of class `"stepFlexmix"` and printing the object gives the information on the number of iterations until termination of the EM algorithm, a logical indicating if the EM algorithm has converged, the log-likelihood and some model information criteria. The plot method compares the fitted models using the different model information criteria.

```
R> betaMixFix
```

Call:

```
stepFlexmix(cbind(Deaths, Total - Deaths) ~ 1 |
  Center, model = FLXMRglmfix(family = "binomial",
  fixed = ~Treatment), data = betablocker, k = 2:4,
  nrep = 5)
```

	iter	converged	k	k0	logLik	AIC	BIC	ICL
2	12	TRUE	2	2	-181.3308	370.6617	377.7984	380.2105
3	9	TRUE	3	3	-159.3605	330.7210	341.4262	343.3257
4	13	TRUE	4	4	-158.2465	332.4929	346.7664	354.4909

A specific `"flexmix"` model contained in the `"stepFlexmix"` object can be selected using `getModel()` with argument `which` to specify the selection criterion. The best model with respect to the BIC is selected with:

```
R> betaMixFix_3 <- getModel(betaMixFix, which = "BIC")
```

In this case a model with three components is selected with respect to the BIC. The fitted values for the model with three components are given in Figure~4 separately for each component and the treatment and control groups.

The fitted parameters of the component specific models can be accessed with:

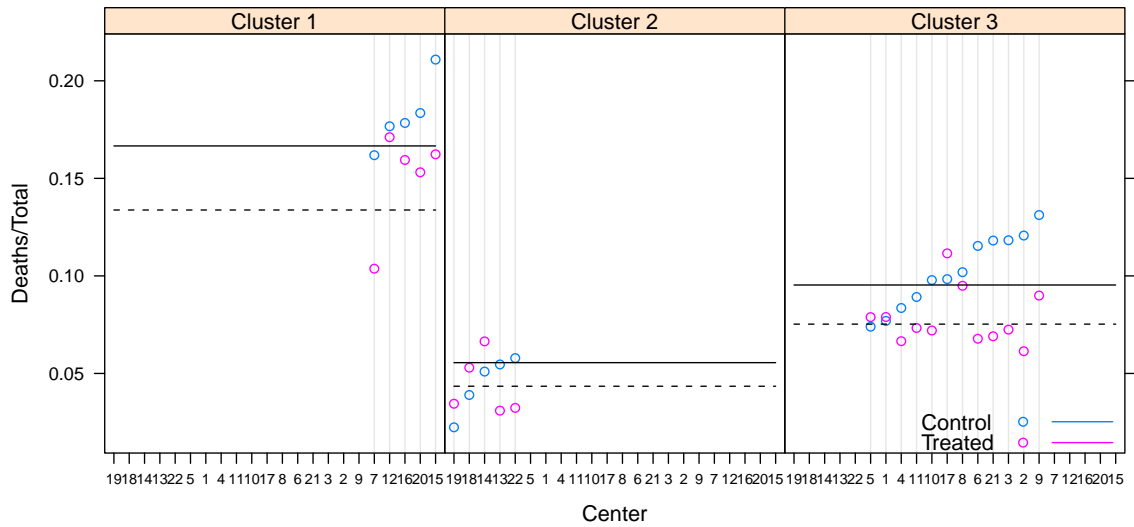


Figure 4: Relative number of deaths for the treatment and the control group for each center in the beta-blocker dataset. The centers are sorted by the relative number of deaths in the control group. The lines indicate the fitted values for each component of the 3-component mixture model with varying intercept and constant parameters for treatment.

```
R> parameters(betaMixFix_3)
```

	Comp.1	Comp.2	Comp.3
coef.TreatmentTreated	-0.2581849	-0.2581849	-0.2581849
coef.(Intercept)	-1.6097872	-2.8336816	-2.2501814

Please note that the coefficients of variable **Treatment** are the same for all three components. The variable **Treatment** can also be included in the varying part of the model. This signifies that a mixture distribution is assumed where for each component different values are allowed for the intercept and the treatment coefficient. This mixture distribution can be specified using function `FLXMRglm()`. Again it is assumed that the heterogeneity is only between centers and therefore the aggregated data for each center can be used.

```
R> betaMix <- stepFlexmix(cbind(Deaths, Total - Deaths) ~ Treatment | Center,
+   model = FLXMRglm(family = "binomial"), k = 3, nrep = 5,
+   data = betablocker)
```

```
3 : * * * * *
```

```
R> parameters(betaMix)
```

	Comp.1	Comp.2	Comp.3
coef.(Intercept)	-2.2476980	-1.5800031	-2.9163372
coef.TreatmentTreated	-0.2630017	-0.3248497	-0.0804783

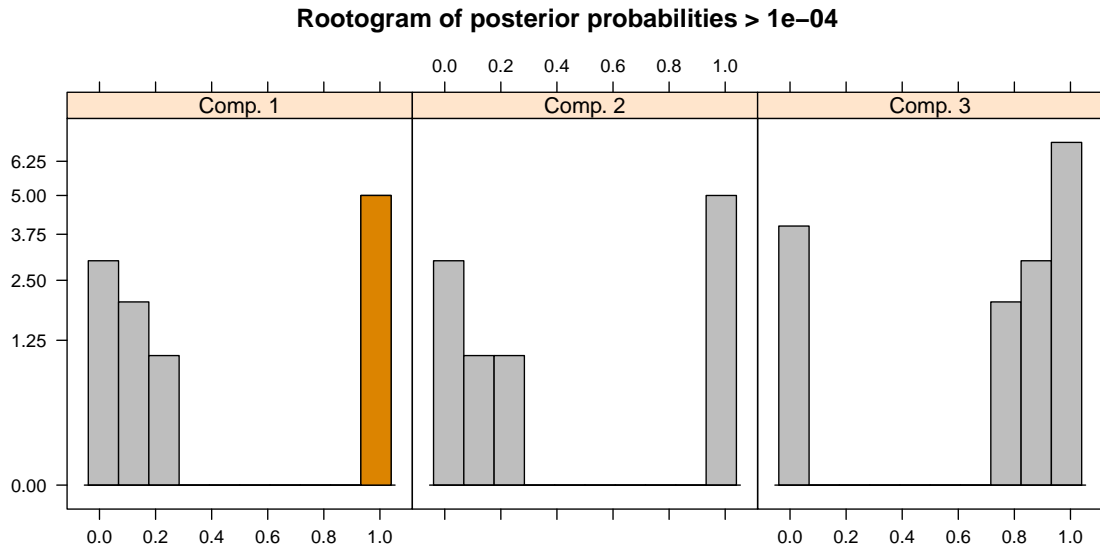


Figure 5: Default plot of "flexmix" objects where the observations assigned to the first component are marked.

```
R> c(BIC(betaMixFix_3), BIC(betaMix))
```

```
[1] 341.4262 346.8925
```

The difference between model `betaMix` and `betaMixFix_3` is that the treatment coefficients are the same for all three components for `betaMixFix_3` while they have different values for `betaMix` which can easily be seen when comparing the fitted component specific parameters. The larger model `betaMix` which also allows varying parameters for treatment has a higher BIC and therefore the smaller model `betaMixFix_3` would be preferred.

The default plot for "flexmix" objects gives a rootogram of the posterior probabilities for each component. Argument `mark` can be used to inspect with which components the specified component overlaps as all observations are coloured in the different panels which are assigned to this component based on the maximum a-posteriori probabilities.

The rootogram indicates that the components are well separated. In Figure~5 it can be seen that component 1 is completely separated from the other two components, while Figure~6 shows that component 3 has a slight overlap with both other components.

The cluster assignments using the maximum a-posteriori probabilities are obtained with:

```
R> table(clusters(betaMix))
```

```
 1  2  3
24 10 10
```

The estimated probabilities of death for each component for the treated patients and those in the control group can be obtained with:

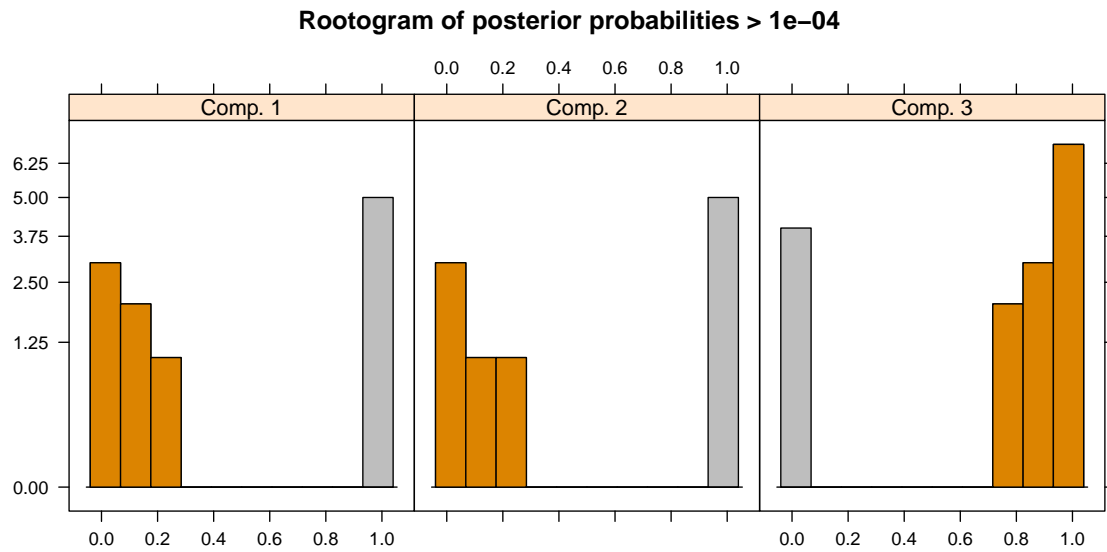


Figure 6: Default plot of "flexmix" objects where the observations assigned to the third component are marked.

```
R> predict(betaMix,
+   newdata = data.frame(Treatment = c("Control", "Treated")))
```

```
$Comp.1
      [,1]
1 0.09554822
2 0.07511149
```

```
$Comp.2
      [,1]
1 0.1707950
2 0.1295602
```

```
$Comp.3
      [,1]
1 0.05135184
2 0.04756995
```

or by obtaining the fitted values for two observations (e.g. ~rows 1 and 23) with the desired levels of the predictor `Treatment`

```
R> betablocker[c(1, 23), ]
```

	Deaths	Total	Center	Treatment
1	3	39	1	Control
23	3	38	1	Treated


```
R> fitted(betaMix)[c(1, 23), ]
```

	Comp.1	Comp.2	Comp.3
[1,]	0.09554822	0.1707950	0.05135184
[2,]	0.07511149	0.1295602	0.04756995

A further analysis of the model is possible with function `refit()` which returns the estimated coefficients together with the standard deviations, z-values and corresponding p-values. Please note that the p-values are only approximate in the sense that they have not been corrected for the fact that the data has already been used to determine the specific fitted model.

```
R> summary(refit(betaMix))
```

\$Comp.1

	Estimate	Std. Error	z value	Pr(> z)
(Intercept)	-2.247678	0.045181	-49.7481	< 2.2e-16
TreatmentTreated	-0.262990	0.065598	-4.0091	6.095e-05

(Intercept) ***
TreatmentTreated ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

\$Comp.2

	Estimate	Std. Error	z value	Pr(> z)
(Intercept)	-1.579965	0.065997	-23.9401	< 2.2e-16
TreatmentTreated	-0.324833	0.092882	-3.4973	0.0004701

(Intercept) ***
TreatmentTreated ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

\$Comp.3

	Estimate	Std. Error	z value	Pr(> z)
(Intercept)	-2.91634	0.09921	-29.3958	<2e-16 ***
TreatmentTreated	-0.08048	0.14104	-0.5706	0.5683

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Given the estimated treatment coefficients we now also compare this model to a model where the treatment coefficient is assumed to be the same for components 1 and 2. Such a model is specified using the model driver `FLXMRglmfix()`. As the first two components are assumed to have the same coefficients for treatment and for the third component the coefficient for treatment shall be set to zero the argument `nested` has `k = c(2,1)` and `formula = c(~Treatment, ~)`.

```

R> ModelNested <- FLXMRglmfix(family = "binomial", nested = list(k = c(2, 1),
+   formula = c(~ Treatment, ~ 0)))
R> betaMixNested <- flexmix(cbind(Deaths, Total - Deaths) ~ 1 | Center,
+   model = ModelNested, k = 3, data = betablocker,
+   cluster = posterior(betaMix))
R> parameters(betaMixNested)

$Comp.1
coef.TreatmentTreated      coef.(Intercept)
          -0.2837779             -2.2379835

$Comp.2
coef.TreatmentTreated      coef.(Intercept)
          -0.2837779             -1.5985089

$Comp.3
coef.(Intercept)
          -2.956159

R> c(BIC(betaMix), BIC(betaMixNested), BIC(betaMixFix_3))

[1] 346.8925 339.9429 341.4262

```

The comparison of the BIC values suggests that the nested model with the same treatment effect for two components and no treatment effect for the third component is the best.

3.3. Productivity of Ph.D.~students in biochemistry

This dataset is taken from [Long \(1990\)](#). It contains 915 observations from academics who obtained their Ph.D.~degree in biochemistry in the 1950s and 60s. It includes 421 women and 494 men. The productivity was measured by counting the number of publications in scientific journals during the three years period ending the year after the Ph.D.~was received. In addition data on the productivity and the prestige of the mentor and the Ph.D.~department was collected. Two measures of family characteristics were recorded: marriage status and number of children of age 5 and lower by the year of the Ph.D.

First, mixtures with one, two and three components and only varying parameters are fitted, and the model minimizing the BIC is selected. This is based on the assumption that unobserved heterogeneity is present in the data due to latent differences between the students in order to be productive and achieve publications. Starting with the most general model to determine the number of components using information criteria and checking for possible model restrictions after having the number of components fixed is a common strategy in finite mixture modelling (see [Wang, Puterman, Cockburn, and Le 1996](#)). Function `refit()` is used to determine confidence intervals for the parameters in order to choose suitable alternative models. However, it has to be noted that in the course of the procedure these confidence intervals will not be correct any more because the specific fitted models have already been determined using the same data.

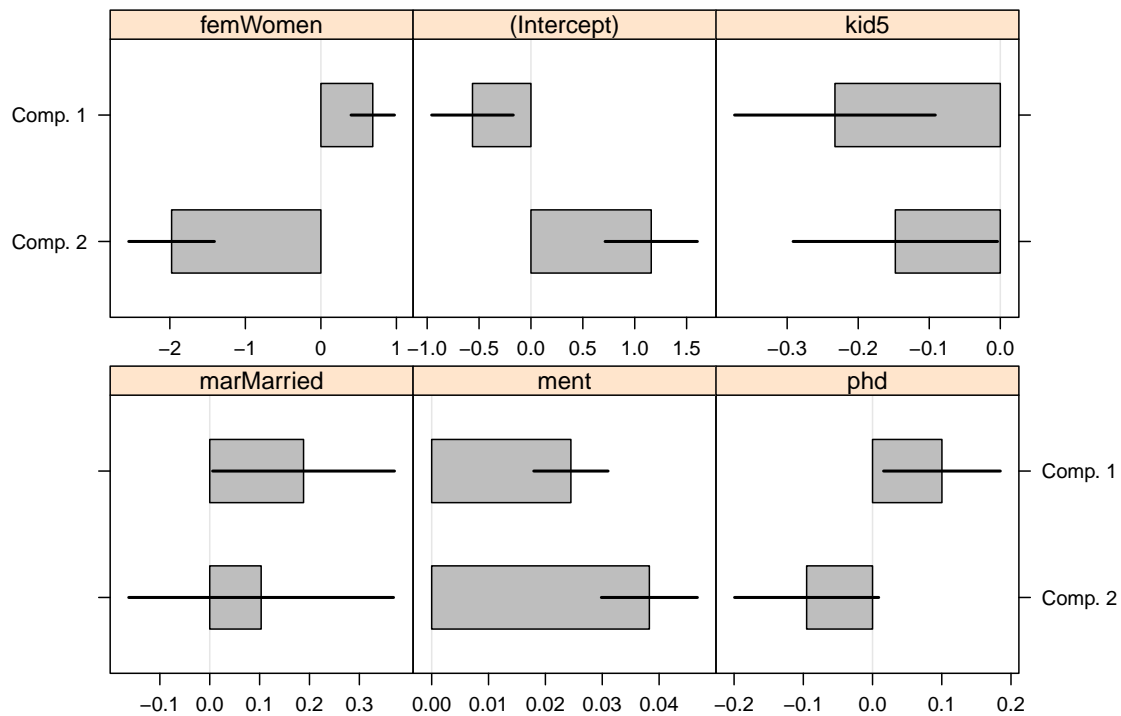


Figure 7: Coefficient estimates and confidence intervals for the model with only varying parameters.

```
R> data("bioChemists")
R> Model1 <- FLXMRglm(family = "poisson")
R> ff_1 <- stepFlexmix(art ~ ., data = bioChemists, k = 1:3, model = Model1)

1 : * * *
2 : * * *
3 : * * *

R> ff_1 <- getModel(ff_1, "BIC")
```

The selected model has 2 components. The estimated coefficients of the components are given in Figure~7 together with the corresponding 95% confidence intervals using the plot method for objects returned by `refit()`. The plot shows that the confidence intervals of the parameters for `kid5`, `mar`, `ment` and `phd` overlap for the two components. In a next step a mixture with two components is therefore fitted where only a varying intercept and a varying coefficient for `fem` is specified and all other coefficients are constant. The EM algorithm is initialized with the fitted mixture model using `posterior()`.

```
R> Model2 <- FLXMRglmfix(family = "poisson", fixed = ~ kid5 + mar + ment)
R> ff_2 <- flexmix(art ~ fem + phd, data = bioChemists,
+   cluster = posterior(ff_1), model = Model2)
R> c(BIC(ff_1), BIC(ff_2))
```

```
[1] 3212.991 3200.071
```

If the BIC is used for model comparison the smaller model including only varying coefficients for the intercept and `fem` is preferred. The coefficients of the fitted model can be obtained using `refit()`:

```
R> summary(refit(ff_2))
```

```
$Comp.1
```

	Estimate	Std. Error	z value	Pr(> z)
kid5	-0.2070933	0.0521307	-3.9726	7.11e-05 ***
marMarried	0.1646178	0.0768505	2.1421	0.0321892 *
ment	0.0274302	0.0032899	8.3377	< 2.2e-16 ***
(Intercept)	-0.4782683	0.2203178	-2.1708	0.0299455 *
femWomen	0.6045078	0.1822082	3.3177	0.0009077 ***
phd	0.0775564	0.0408161	1.9001	0.0574148 .

```
---
```

```
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
$Comp.2
```

	Estimate	Std. Error	z value	Pr(> z)
kid5	-0.2070933	0.0521307	-3.9726	7.110e-05 ***
marMarried	0.1646178	0.0768505	2.1421	0.03219 *
ment	0.0274302	0.0032899	8.3377	< 2.2e-16 ***
(Intercept)	1.3208461	0.2337508	5.6507	1.598e-08 ***
femWomen	-2.2054873	0.4313329	-5.1132	3.168e-07 ***
phd	-0.0818211	0.0554627	-1.4752	0.14015

```
---
```

```
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

It can be seen that the coefficient of `phd` does for both components not differ significantly from zero and might be omitted. This again improves the BIC.

```
R> Model3 <- FLXMRglmfix(family = "poisson", fixed = ~ kid5 + mar + ment)
R> ff_3 <- flexmix(art ~ fem, data = bioChemists, cluster = posterior(ff_2),
+   model = Model3)
R> c(BIC(ff_2), BIC(ff_3))
```

```
[1] 3200.071 3192.816
```

The coefficients of the restricted model without `phd` are given in Figure~8.

An alternative model would be to assume that gender does not directly influence the number of articles but has an impact on the segment sizes.

```
R> Model4 <- FLXMRglmfix(family = "poisson", fixed = ~ kid5 + mar + ment)
R> ff_4 <- flexmix(art ~ 1, data = bioChemists, cluster = posterior(ff_2),
+   concomitant = FLXPmultinom(~ fem), model = Model4)
R> parameters(ff_4)
```

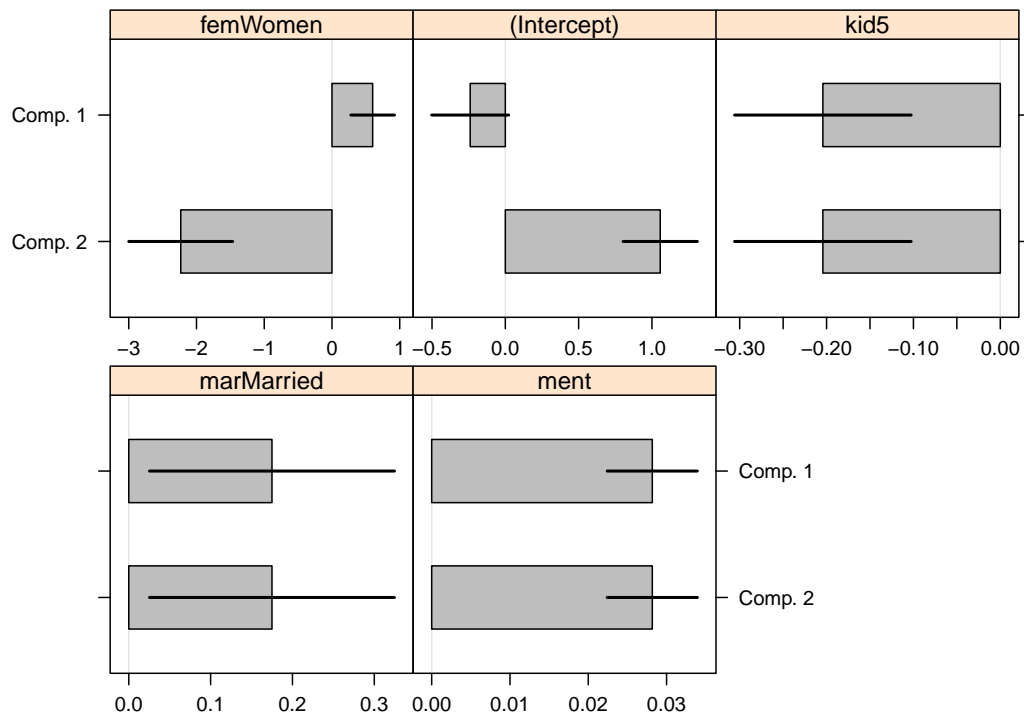


Figure 8: Coefficient estimates and confidence intervals for the model with varying and constant parameters where the variable `phd` is not used in the regression.

	Comp.1	Comp.2
<code>coef.kid5</code>	-0.1819162	-0.1819162
<code>coef.marMarried</code>	0.1883990	0.1883990
<code>coef.ment</code>	0.0288501	0.0288501
<code>coef.(Intercept)</code>	-0.2583828	0.9950050

```
R> summary(refit(ff_4), which = "concomitant")
```

```
$Comp.2
```

	Estimate	Std. Error	z value	Pr(> z)
(Intercept)	-1.02262	0.28385	-3.6027	0.0003149 ***
femWomen	-0.61281	0.27280	-2.2464	0.0246782 *

```
---
```

```
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
R> BIC(ff_4)
```

```
[1] 3182.328
```

This suggests that the proportion of women is lower in the second component which is the more productive segment.

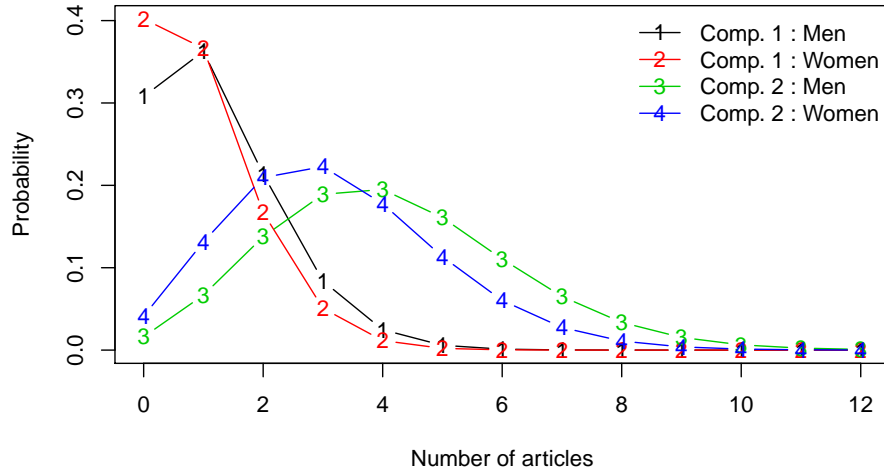


Figure 9: The estimated productivity for each component for men and women.

The alternative modelling strategy where homogeneity is assumed at the beginning and a varying intercept is added if overdispersion is observed leads to the following model which is the best with respect to the BIC.

```
R> Model15 <- FLXMRglmfix(family = "poisson", fixed = ~ kid5 + ment + fem)
R> ff_5 <- flexmix(art ~ 1, data = bioChemists, cluster = posterior(ff_2),
+   model = Model15)
R> BIC(ff_5)
```

```
[1] 3174.266
```

In Figure~9 the estimated distribution of productivity for model `ff_5` are given separately for men and women as well as for each component where for all other variables the mean values are used for the numeric variables and the most frequent category for the categorical variables. The two components differ in that component 1 contains the students who publish no article or only a single article, while the students in component 2 write on average several articles. With a constant coefficient for gender women publish less articles than men in both components.

This example shows that different optimal models are chosen for different modelling procedures. However, the distributions induced by the different variants of the model class may be similar and therefore it is not surprising that they then will have similar BIC values.

4. Implementation

The new features extend the available model class described in [Leisch \(2004b\)](#) by providing infrastructure for concomitant variable models and for fitting mixtures of GLMs with varying

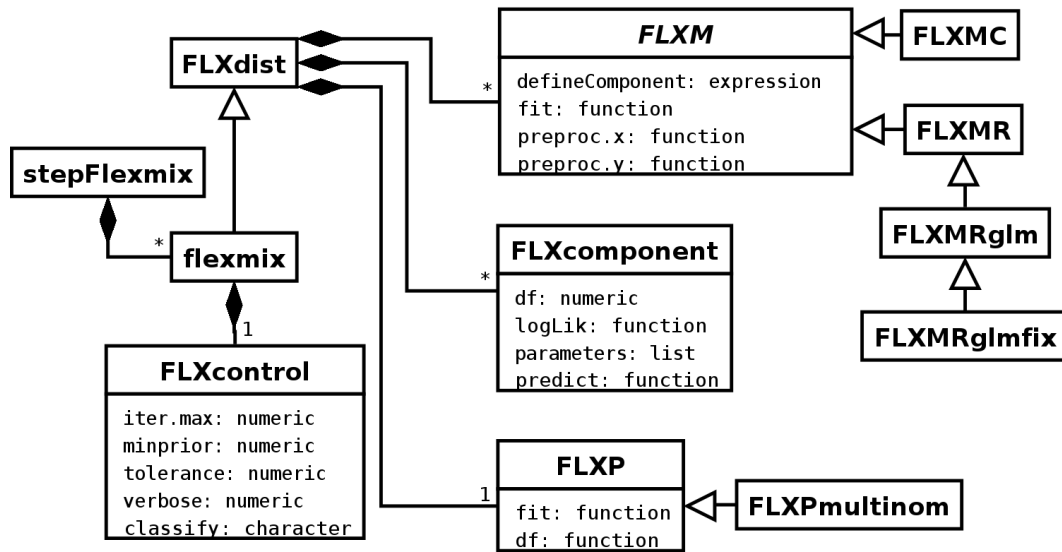


Figure 10: UML class diagram (see [Fowler 2004](#)) of the **flexmix** package.

and constant parameters for the component specific parameters. The implementation of the extensions of the model class made it necessary to define a better class structure for the component specific models and to modify the fit functions `flexmix()` and `FLXfit()`.

An overview on the S4 class structure of the package is given in Figure~10. There is a class for unfitted finite mixture distributions given by "**FLXdist**" which contains a list of "**FLXMC**" objects which determine the component specific models, a list of "**FLXcomponent**" objects which specify functions to determine the component specific log-likelihoods and predictions and which contain the component specific parameters, and an object of class "**FLXP**" which specifies the concomitant variable model. Class "**flexmix**" extends "**FLXdist**". It represents a fitted finite mixture distribution and it contains the information about the fitting with the EM algorithm in the object of class "**FLXcontrol**". Repeated fitting with the EM algorithm with different number of components is provided by function `stepFlexmix()` which returns an object of class "**stepFlexmix**". Objects of class "**stepFlexmix**" contain the list of the fitted mixture models for each number of components in the slot "**models**".

For the component specific model a virtual class "**FLXM**" is introduced which (currently) has two subclasses: "**FLXMC**" for model-based clustering and "**FLXMR**" for clusterwise regression, where predictor variables are given. Additional slots have been introduced to allow for data preprocessing and the construction of the components was separated from the fit and is now captured as an expression (to allow for lexical scoping; [Gentleman and Ihaka 2000](#)) in the slot `defineComponent`. "**FLXMC**" has an additional slot `dist` to specify the name of the distribution of the variable. In the future functionality shall be provided for sampling from a fitted or unfitted finite mixture. Using this slot observations can be generated by using the function which results from adding an `r` at the beginning of the distribution name. This allows to only implement the (missing) random number generator functions and otherwise use the same method for sampling from mixtures with component specific models of class "**FLXMC**".

For `flexmix()` and `FLXfit()` code blocks which are model dependent have been identified and different methods implemented. Finite mixtures of regressions with varying, nested and

constant parameters were a suitable model class for this identification task as they are different from models previously implemented. The main differences are:

- The number of components is related to the component specific model and the omission of small components during the EM algorithm impacts on the model.
- The parameters of the component specific models can not be determined separately in the M-step and a joint model matrix is needed.

This makes it also necessary to have different model dependent methods for `fitted()` which extracts the fitted values from a "flexmix" object, `predict()` which predicts new values for a "flexmix" object and `refit()` which refits an estimated model to obtain additional information for a "flexmix" object.

4.1. Component specific models with varying and constant parameters

A new M-step driver is provided which fits finite mixtures of GLMs with constant and nested varying parameters for the coefficients and the dispersion parameters. The class "FLXMRglmfix" returned by the driver `FLXMRglmfix()` has the following additional slots with respect to "FLXMRglm":

design: An incidence matrix indicating which columns of the model matrix are used for which component, i.e. $\tilde{\mathbf{D}} = (\mathbf{1}_K, \mathbf{J}, \mathbf{I}_K)$.

nestedformula: An object of class "FLXnested" containing the formula for the nested regression coefficients and the number of components in each K_c , $c \in C$.

fixed: The formula for the constant regression coefficients.

variance: A logical indicating if different variances shall be estimated for the components following a Gaussian distribution or a vector specifying the nested structure for estimating these variances.

The difference between estimating finite mixtures including only varying parameters using models specified with `FLXMRglm()` and those with varying and constant parameters using function `FLXMRglmfix()` is hidden from the user, as only the specified model is different. The fitted model is also of class "flexmix" and can be analyzed using the same functions as for any model fitted using package **flexmix**. The methods used are the same except if the slot containing the model is accessed and method dispatching is made via the model class. New methods are provided for models of class "FLXMRglmfix" for functions `refit()`, `fitted()` and `predict()` which can be used for analyzing the fitted model.

The implementation allows repeated measurements by specifying a grouping variable in the formula argument of `flexmix()`. Furthermore, it has to be noticed that the model matrix is determined by updating the formula of the varying parameters successively with the formula of the constant and then of the nested varying parameters. This ensures that if a mixture distribution is fitted for the intercept, the model matrix of a categorical variable includes only the remaining columns for the constant parameters to have full column rank. However, this updating scheme makes it impossible to estimate a constant intercept while allowing varying parameters for a categorical variable.

For this model one big model matrix is constructed where the observations are repeated K times and suitable columns of zero added. The coefficients of all K components are determined simultaneously in the M-step, while if only varying parameters are specified the maximization of the likelihood is made separately for all components. For large datasets the estimation of a combination of constant and varying parameters might therefore be more challenging than only varying parameters.

4.2. Concomitant variable models

For representing concomitant variable models the class "FLXP" is defined. It specifies how the concomitant variable model is fitted using the concomitant variable model matrix as predictor variables and the current a-posteriori probability estimates as response variables. The object has the following slots:

fit: A function (x , y , ...) returning the fitted values for the component weights during the EM algorithm.

refit: A function (x , y , ...) used for refitting the model.

df: A function (x , k , ...) returning the degrees of freedom used for estimating the concomitant variable model given the model matrix x and the number of components k .

x: A matrix containing the model matrix of the concomitant variables.

formula: The formula for determining the model matrix x .

name: A character string describing the model, which is only used for print output.

Two constructor functions for concomitant variable models are provided at the moment. `FLXPconstant()` is for constant component weights without concomitant variables and for multinomial logit models `FLXPmultinom()` can be used. `FLXPmultinom()` has its own class "FLXPmultinom" which extends "FLXP" and has an additional slot `coef` for the fitted coefficients. The multinomial logit models are fitted using package **nnet** (Venables and Ripley 2002).

4.3. Further changes

The estimation of the model with the EM algorithm was improved by adapting the variants to correspond to the CEM and SEM variants as outlined in the literature. To make this more explicit it is now also possible to use "CEM" or "SEM" to specify an EM variant in the `classify` argument of the "FLXcontrol" object. Even though the SEM algorithm can in general not be expected to converge the fitting procedure is also terminated for the SEM algorithm if the change in the relative log-likelihood is smaller than the pre-specified threshold. This is motivated by the fact that for well separated clusters the posteriors might converge to an indicator function with all weight concentrated in one component. The fitted model with the maximum likelihood encountered during the SEM algorithm is returned.

For discrete data in general multiple observations with the same values are given in a dataset. A `weights` argument was added to the fitting function `flexmix()` in order to avoid repeating

these observations in the provided dataset. The specification is through a `formula` in order to allow selecting a column of the data frame given in the `data` argument. The weights argument allows to avoid replicating the same observations and hence enables more efficient memory use in these applications. This possibitliy is especially useful in the context of model-based clustering for mixtures of Poisson distributions or latent class analysis with multivariate binary observations.

In order to be able to apply different initialization strategies such as for example first running several different random initializations with CEM and then switching to ordinary EM using the best solution found by CEM for initialization a `posterior()` function was implemented. `posterior()` also takes a `newdata` argument and hence, it is possible to apply subset strategies for large datasets as suggested in Wehrens, Buydens, Fraley, and Raftery (2004). The returned matrix of the posterior probabilities can be used to specify the `cluster` argument for `flexmix()` and the posteriors are then used as weights in the first M-step.

The default plot methods now use trellis graphics as implemented in package **lattice** (Sarkar 2008). Users familiar with the syntax of these graphics and with the plotting and printing arguments will find the application intuitive as a lot of plotting arguments are passed to functions from **lattice** as for example `xyplot()` and `histogram()`. In fact only new panel, pre-panel and group-panel functions were implemented. The returned object is of class `"trellis"` and the `show` method for this class is used to create the plot.

Function `refit()` was modified and has now two different estimation methods: `"optim"` and `"mstep"`. The default method `"optim"` determines the variance-covariance matrix of the parameters from the inverse Hessian of the full log-likelihood. The general purpose optimizer `optim()` is used to maximize the log-likelihood and initialized in the solution obtained with the EM algorithm. For mixtures of GLMs there are also functions implemented to determine the gradient which can be used to speed up convergence.

The second method `"mstep"` is only a raw approximation. It performs an M-step where the a-posteriori probabilities are treated as given instead of estimated and returns for the component specific models nearly complete `"glm"` objects which can be further analyzed. The advantage of this method is that the return value is basically a list of standard `"glm"` objects, such that the regular methods for this class can be used.

5. Writing your own drivers

Two examples are given in the following to demonstrate how new drivers can be provided for concomitant variable models and for component specific models. Easy extensibility is one of the main implementation aims of the package and it can be seen that writing new drivers requires only a few lines of code for providing the constructor functions which include the fit functions.

5.1. Component specific models: Zero-inflated models

In Poisson or binomial regression models it can be often encountered that the observed number of zeros is higher than expected. A mixture with two components where one has mean zero can be used to model such data. These models are also referred to as zero-inflated models (see for example Böhning, Dietz, Schlattmann, Mendonça, and Kirchner 1999). A generalization of this model class would be to fit mixtures with more than two components where one

component has a mean fixed at zero. So this model class is a special case of a mixture of generalized linear models where (a) the family is restricted to Poisson and binomial and (b) the parameters of one component are fixed. For simplicity the implementation assumes that the component with mean zero is the first component. In addition we assume that the model matrix contains an intercept and to have the first component absorbing the excess zeros the coefficient of the intercept is set to $-\infty$ and all other coefficients are set to zero.

Hence, to implement this model using package **flexmix** an appropriate model class is needed with a corresponding convenience function for construction. During the fitting of the EM algorithm using `flexmix()` different methods for this model class are needed when determining the model matrix (to check the presence of an intercept), to check the model after a component is removed and for the M-step to account for the fact that the coefficients of the first component are fixed. For all other methods those available for "FLXMRglm" can be re-used. The code is given in Figure~11.

The model class "FLXMRziglm" is defined as extending "FLXMRglm" in order to be able to inherit methods from this model class. For construction of a "FLXMRziglm" class the convenience function `FLXMRziglm()` is used which calls `FLXMRglm()`. The only differences are that the family is restricted to binomial or Poisson, that a different name is assigned and that an object of the correct class is returned.

The presence of the intercept in the model matrix is checked in `FLXgetModelmatrix()` after using the method available for "FLXMRglm" models as indicated by the call to `callNextMethod()`. During the EM algorithm `FLXremoveComponent()` is called if one component is removed. For this model class it checks if the first component has been removed and if this is the case the model class is changed to "FLXMRglm".

In the M-step the coefficients of the first component are fixed and not estimated, while for the remaining components the M-step of "FLXMRglm" objects can be used. During the EM algorithm `FLXmstep()` is called to perform the M-step and returns a list of "FLXcomponent" objects with the fitted parameters. A new method for this function is needed for "FLXMRziglm" objects in order to account for the fixed coefficients in the first component, i.e.~for the first component the "FLXcomponent" object is constructed and concatenated with the list of "FLXcomponent" objects returned by using the `FLXmstep()` method for "FLXMRglm" models for the remaining components.

Similar modifications are necessary in order to be able to use `refit()` for this model class. The code for implementing the `refit()` method using `optim()` for "FLXMRziglm" is not shown, but can be inspected in the source code of the package.

Example: Using the driver

This new M-step driver can be used to estimate a zero-inflated Poisson model to the data given in [Böhning *et al.* \(1999\)](#). The dataset `dmft` consists of count data from a dental epidemiological study for evaluation of various programs for reducing caries collected among school children from an urban area of Belo Horizonte (Brazil). The variables included are the number of decayed, missing or filled teeth (DMFT index) at the beginning and at the end of the observation period, the gender, the ethnic background and the specific treatment for 797 children.

The model can be fitted with the new driver function using the following commands:

```

1  setClass("FLXMRziglm", contains = "FLXMRglm")

   FLXMRziglm <- function(formula = . ~ .,
                           family = c("binomial", "poisson"), ...)
   {
6    family <- match.arg(family)
      new("FLXMRziglm", FLXMRglm(formula, family, ...),
          name = paste("FLXMRziglm", family, sep=":"))
   }

11  setMethod("FLXgetModelmatrix", signature(model="FLXMRziglm"),
        function(model, data, formula, lhs=TRUE, ...)
        {
            model <- callNextMethod(model, data, formula, lhs)
            if (attr(terms(model@fullformula), "intercept") == 0)
16              stop("please include an intercept")
            model
        })

   setMethod("FLXremoveComponent", signature(model = "FLXMRziglm"),
21         function(model, nok, ...)
        {
            if (1 %in% nok) as(model, "FLXMRglm") else model
        })

26  setMethod("FLXmstep", signature(model = "FLXMRziglm"),
        function(model, weights, ...)
        {
            coef <- c(-Inf, rep(0, ncol(model@x)-1))
            names(coef) <- colnames(model@x)
31            comp.1 <- with(list(coef = coef, df = 0, offset = NULL,
                                family = model@family), eval(model@defineComponent))
            c(list(comp.1),
              FLXmstep(as(model, "FLXMRglm"), weights[, -1, drop=FALSE]))
        })

```

Figure 11: Driver for a zero-inflated component specific model.

```
R> data("dmft")
R> Model <- FLXMRzglm(family = "poisson")
R> Fitted <- flexmix(End ~ log(Begin + 0.5) + Gender + Ethnic + Treatment,
+   model = Model, k = 2, data = dmft, control = list(minprior = 0.01))
R> summary(refit(Fitted))
```

```
$Comp.2
```

	Estimate	Std. Error	z value	Pr(> z)
(Intercept)	-0.1470652	0.0963031	-1.5271	0.126734
log(Begin + 0.5)	0.7303431	0.0402403	18.1496	< 2.2e-16
Gendermale	0.0068805	0.0550486	0.1250	0.900531
Ethnicwhite	0.0500281	0.0592975	0.8437	0.398848
Ethnicblack	-0.0472578	0.0899984	-0.5251	0.599516
Treatmenteduc	-0.2371848	0.0905877	-2.6183	0.008837
Treatmentall	-0.3277747	0.1011637	-3.2400	0.001195
Treatmentenrich	0.0172642	0.0838730	0.2058	0.836918
Treatmentrinse	-0.2414627	0.0871032	-2.7721	0.005569
Treatmenthygiene	-0.1026315	0.0916676	-1.1196	0.262882

```
(Intercept)
log(Begin + 0.5) ***
Gendermale
Ethnicwhite
Ethnicblack
Treatmenteduc **
Treatmentall **
Treatmentenrich
Treatmentrinse **
Treatmenthygiene
---
```

```
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Please note that [Böhning *et al.* \(1999\)](#) added the predictor $\log(\text{Begin} + 0.5)$ to serve as an offset in order to be able to analyse the improvement in the DMFT index from the beginning to the end of the study. The linear predictor with the offset subtracted is intended to be an estimate for $\log(\mathbb{E}(\text{End})) - \log(\mathbb{E}(\text{Begin}))$. This is justified by the fact that for a Poisson distributed variable Y with mean between 1 and 10 it holds that $\mathbb{E}(\log(Y + 0.5))$ is approximately equal to $\log(\mathbb{E}(Y))$. $\log(\text{Begin} + 0.5)$ can therefore be seen as an estimate for $\log(\mathbb{E}(\text{Begin}))$.

The estimated coefficients with corresponding confidence intervals are given in Figure~12. As the coefficients of the first component are restricted a-priori to minus infinity for the intercept and to zero for the other variables, they are of no interest and only the second component is plotted. The box ratio can be modified as for `barchart()` in package **lattice**. The code to produce this plot is given by:

```
R> print(plot(refit(Fitted), components = 2, box.ratio = 3))
```

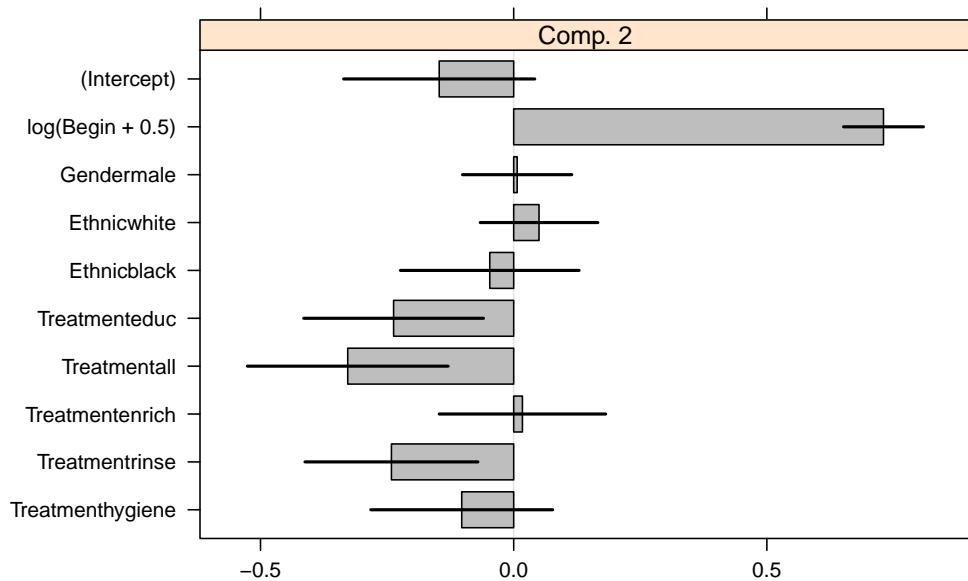


Figure 12: The estimated coefficients of the zero-inflated model for the `dmft` dataset. The first component is not plotted as this component captures the inflated zeros and its coefficients are fixed a-priori.

5.2. Concomitant variable models

If the concomitant variable is a categorical variable, the multinomial logit model is equivalent to a model where the component weights for each level of the concomitant variable are determined by the mean values of the a-posteriori probabilities. The driver which implements this "FLXP" model is given in Figure~13. A name for the driver has to be specified and a `fit()` function. In the `fit()` function the mean posterior probability for all observations with the same covariate points is determined, assigned to the corresponding observations and the full new a-posteriori probability matrix returned. By contrast `refit()` only returns the new a-posteriori probability matrix for the number of unique covariate points.

Example: Using the driver

If the concomitant variable model returned by `myConcomitant()` is used for the artificial example in Section~3 the same fitted model is returned as if a multinomial logit model is specified. An advantage is that in this case no problems occur if the fitted probabilities are close to zero or one.

```
R> Concomitant <- FLXPmultinom(~ yb)
R> MyConcomitant <- myConcomitant(~ yb)
R> m2 <- flexmix(. ~ x, data = NPreg, k = 2, model = list(Model_n, Model_p),
+   concomitant = Concomitant)
R> m3 <- flexmix(. ~ x, data = NPreg, k = 2, model = list(Model_n, Model_p),
+   cluster = posterior(m2), concomitant = MyConcomitant)
```



```

myConcomitant <-
function(formula = ~ 1) {
  z <- new("FLXP",
4         name = "myConcomitant",
          formula = formula)
  z@fit <- function(x, y, w, ...) {
    if (missing(w) || is.null(w)) w <- rep(1, length(x))
    f <- as.integer(factor(apply(x, 1, paste,
9                                collapse = "")))

    AVG <- apply(w*y, 2, tapply, f, mean)
    (AVG/rowSums(AVG))[f,,drop=FALSE]
  }
  z@refit <- function(x, y, w, ...) {
14    if (missing(w) || is.null(w)) w <- rep(1, length(x))
    f <- as.integer(factor(apply(x, 1, paste,
                                collapse = "")))

    AVG <- apply(w*y, 2, tapply, f, mean)
    (AVG/rowSums(AVG))
19  }
  z
}

```

Figure 13: Driver for a concomitant variable model where the component weights are determined by averaging over the a-posteriori probabilities for each level of the concomitant variable.

```
R> summary(m2)
```

Call:

```
flexmix(formula = . ~ x, data = NPreg, k = 2,
        model = list(Model_n, Model_p), concomitant = Concomitant)
```

	prior	size	post>0	ratio
Comp.1	0.493	96	138	0.696
Comp.2	0.507	104	137	0.759

```
'log Lik.' -1044.724 (df=14)
AIC: 2117.448    BIC: 2163.625
```

```
R> summary(m3)
```

Call:

```
flexmix(formula = . ~ x, data = NPreg, k = 2,
        cluster = posterior(m2), model = list(Model_n,
        Model_p), concomitant = MyConcomitant)
```

	prior	size	post>0	ratio
Comp.1	0.493	96	138	0.696
Comp.2	0.507	104	137	0.759

```
'log Lik.' -1044.724 (df=14)
AIC: 2117.448    BIC: 2163.625
```

For comparing the estimated component weights for each value of *y_b* the following function can be used:

```
R> determinePrior <- function(object) {
+   object@concomitant@fit(object@concomitant@x,
+   posterior(object))['!duplicated(object@concomitant@x), ]
+ }
```

```
R> determinePrior(m2)
```

```
      [,1]      [,2]
1 0.4830052 0.5169948
4 0.5050200 0.4949800
```

```
R> determinePrior(m3)
```

```
      [,1]      [,2]
1 0.4830037 0.5169963
2 0.5050168 0.4949832
```

Obviously the fitted values of the two models correspond to each other.

6. Summary and outlook

Package **flexmix** was extended to cover finite mixtures of GLMs with (nested) varying and constant parameters. This allows for example the estimation of varying intercept models. In order to be able to characterize the components given some variables concomitant variable models can be estimated for the component weights.

The implementation of these extensions have triggered some modifications in the class structure and in the fit functions `flexmix()` and `FLXfit()`. For certain steps, as e.g. the M-step, methods which depend on the component specific models are defined in order to enable the estimation of finite mixtures of GLMs with only varying parameters and those with (nested) varying and constant parameters with the same fit function. The flexibility of this modified implementation is demonstrated by illustrating how a driver for zero-inflated models can be defined.

In the future diagnostic tools based on resampling methods shall be implemented as bootstrap results can give valuable insights into the model fit (Grün and Leisch 2004). A function which conveniently allows to test linear hypotheses about the parameters using the variance-covariance matrix returned by `refit()` would be a further valuable diagnostic tool.

The implementation of zero-inflated Poisson and binomial regression models are a first step towards relaxing the assumption that all component specific distributions are from the same

parametric family. As mixtures with components which follow distributions from different parametric families can be useful for example to model outliers (Dasgupta and Raftery 1998; Leisch 2008), it is intended to also make this functionality available in **flexmix** in the future.

Computational details

All computations and graphics in this paper have been done using R version 2.11.1 with the packages **nnet** 7.3-1, **ellipse** 0.3-5, **flexmix** 2.2-10, **multcomp** 1.2-3, **survival** 2.35-8, **mvtnorm** 0.9-92, **modeltools** 0.2-17, **lattice** 0.19-13.

Acknowledgments

This research was supported by the the Austrian Science Foundation (FWF) under grants P17382 and T351. Thanks also to Achim Zeileis for helpful discussions on implementation details and an anonymous referee for asking a good question about parameter significance which initiated the new version of function `refit()`.

References

- Aitkin M (1999a). “A General Maximum Likelihood Analysis of Variance Components in Generalized Linear Models.” *Biometrics*, **55**, 117–128.
- Aitkin M (1999b). “Meta-Analysis by Random Effect Modelling in Generalized Linear Models.” *Statistics in Medicine*, **18**(17–18), 2343–2351.
- Biernacki C, Celeux G, Govaert G (2000). “Assessing a Mixture Model for Clustering with the Integrated Completed Likelihood.” *IEEE Transactions on Pattern Analysis and Machine Intelligence*, **22**(7), 719–725.
- Biernacki C, Celeux G, Govaert G (2003). “Choosing Starting Values for the EM Algorithm for Getting the Highest Likelihood in Multivariate Gaussian Mixture Models.” *Computational Statistics & Data Analysis*, **41**, 561–575.
- Böhning D (1999). *Computer Assisted Analysis of Mixtures and Applications: Meta-Analysis, Disease Mapping, and Others*, volume 81 of *Monographs on Statistics and Applied Probability*. Chapman & Hall/CRC, London.
- Böhning D, Dietz E, Schlattmann P, Mendonça L, Kirchner U (1999). “The Zero-Inflated Poisson Model and the Decayed, Missing and Filled Teeth Index in Dental Epidemiology.” *Journal of the Royal Statistical Society A*, **162**(2), 195–209.
- Celeux G, Diebolt J (1988). “A Random Imputation Principle: The Stochastic EM Algorithm.” *Rapports de Recherche 901*, INRIA.
- Celeux G, Govaert G (1992). “A Classification EM Algorithm for Clustering and Two Stochastic Versions.” *Computational Statistics & Data Analysis*, **14**(3), 315–332.

- Chambers JM (1998). *Programming with Data*. Springer-Verlag, New York. ISBN 0-387-98503-4.
- Dasgupta A, Raftery AE (1998). “Detecting Features in Spatial Point Processes with Clutter Via Model-Based Clustering.” *Journal of the American Statistical Association*, **93**(441), 294–302.
- Dayton CM, Macready GB (1988). “Concomitant-Variable Latent-Class Models.” *Journal of the American Statistical Association*, **83**(401), 173–178.
- Dempster AP, Laird NM, Rubin DB (1977). “Maximum Likelihood from Incomplete Data Via the EM-Algorithm.” *Journal of the Royal Statistical Society B*, **39**, 1–38.
- Diebolt J, Ip EHS (1996). “Stochastic EM: Method and Application.” In W R Gilks, S Richardson, D J Spiegelhalter (eds.), “Markov Chain Monte Carlo in Practice,” pp. 259–273. Chapman and Hall.
- Everitt BS, Hand DJ (1981). *Finite Mixture Distributions*. Chapman and Hall, London.
- Follmann DA, Lambert D (1989). “Generalizing Logistic Regression by Non-Parametric Mixing.” *Journal of the American Statistical Association*, **84**(405), 295–300.
- Follmann DA, Lambert D (1991). “Identifiability of Finite Mixtures of Logistic Regression Models.” *Journal of Statistical Planning and Inference*, **27**(3), 375–381.
- Fowler M (2004). *UML Distilled: A Brief Guide to the Standard Object Modeling Language*. Addison-Wesley Professional, 3rd edition.
- Frühwirth-Schnatter S (2006). *Finite Mixture and Markov Switching Models*. Springer-Verlag Series in Statistics. Springer-Verlag, New York. ISBN 0-387-32909-9.
- Gentleman R, Ihaka R (2000). “Lexical Scope and Statistical Computing.” *Journal of Computational and Graphical Statistics*, **9**(3), 491–508.
- Grün B (2006). *Identification and Estimation of Finite Mixture Models*. Ph.D. thesis, Institut für Statistik und Wahrscheinlichkeitstheorie, Technische Universität Wien. Friedrich Leisch, advisor.
- Grün B, Leisch F (2004). “Bootstrapping Finite Mixture Models.” In J Antoch (ed.), “COMPSTAT 2004 – Proceedings in Computational Statistics,” pp. 1115–1122. Physica Verlag, Heidelberg. ISBN 3-7908-1554-3.
- Grün B, Leisch F (2006). “Fitting Finite Mixtures of Linear Regression Models with Varying & Fixed Effects in R.” In A Rizzi, M Vichi (eds.), “COMPSTAT 2006 – Proceedings in Computational Statistics,” pp. 853–860. Physica Verlag, Heidelberg, Germany. ISBN 3-7908-1708-2.
- Grün B, Leisch F (2007). “Fitting Finite Mixtures of Generalized Linear Regressions in R.” *Computational Statistics & Data Analysis*, **51**(11), 5247–5252.
- Grün B, Leisch F (2008a). “Identifiability of Finite Mixtures of Multinomial Logit Models with Varying and Fixed Effects.” *Journal of Classification*. Accepted for publication on 2008-03-28.

- Grün B, Leisch F (2008b). “**FlexMix** Version 2: Finite Mixtures with Concomitant Variables and Varying and Constant Parameters.” *Journal of Statistical Software*, **28**(4), 1–35. URL <http://www.jstatsoft.org/v28/i04/>.
- Harrell FE (2001). *Regression Modeling Strategies*. Springer-Verlag, New York.
- Hastie T, Tibshirani R (1993). “Varying-Coefficient Models.” *Journal of the Royal Statistical Society B*, **55**(4), 757–796.
- Karlis D, Xekalaki E (2003). “Choosing Initial Values for the EM Algorithm for Finite Mixtures.” *Computational Statistics & Data Analysis*, **41**, 577–590.
- Leisch F (2002). “Sweave: Dynamic Generation of Statistical Reports Using Literate Data Analysis.” In W~Härdle, B~Rönz (eds.), “COMPSTAT 2002 – Proceedings in Computational Statistics,” pp. 575–580. Physica Verlag, Heidelberg. ISBN 3-7908-1517-9.
- Leisch F (2003). “Sweave, Part II: Package Vignettes.” *R News*, **3**(2), 21–24. URL <http://CRAN.R-project.org/doc/Rnews/>.
- Leisch F (2004a). “Exploring the Structure of Mixture Model Components.” In J~Antoch (ed.), “COMPSTAT 2004 – Proceedings in Computational Statistics,” pp. 1405–1412. Physica Verlag, Heidelberg. ISBN 3-7908-1554-3.
- Leisch F (2004b). “**FlexMix**: A General Framework for Finite Mixture Models and Latent Class Regression in R.” *Journal of Statistical Software*, **11**(8), 1–18. URL <http://www.jstatsoft.org/v11/i08/>.
- Leisch F (2008). “Modelling Background Noise in Finite Mixtures of Generalized Linear Regression Models.” In P~Brito (ed.), “COMPSTAT 2008 – Proceedings in Computational Statistics,” volume~I, pp. 385–396. Physica Verlag, Heidelberg, Germany. ISBN 978-3-7908-2083-6.
- Long JS (1990). “The Origins of Sex Differences in Science.” *Social Forces*, **68**(4), 1297–1315.
- McCullagh P, Nelder JA (1989). *Generalized Linear Models*. Chapman and Hall, 2nd edition.
- McLachlan GJ, Basford KE (1988). *Mixture Models: Inference and Applications to Clustering*. Marcel Dekker, New York.
- McLachlan GJ, Peel D (2000). *Finite Mixture Models*. John Wiley & Sons.
- Pinheiro JC, Bates DM (2000). *Mixed-Effects Models in S and S-Plus*. Springer-Verlag. ISBN 0-387-98957-0.
- Sarkar D (2008). *lattice: Multivariate Data Visualization with R*. Springer-Verlag, New York. ISBN 978-0-387-75968-5.
- Titterton DM, Smith AFM, Makov UE (1985). *Statistical Analysis of Finite Mixture Distributions*. John Wiley & Sons.
- Venables WN, Ripley BD (2002). *Modern Applied Statistics with S*. Springer-Verlag, New York, 4th edition. ISBN 0-387-95457-0.

- Wang P, Puterman ML, Cockburn IM, Le ND (1996). “Mixed Poisson Regression Models with Covariate Dependent Rates.” *Biometrics*, **52**, 381–400.
- Wedel M, DeSarbo WS (1995). “A Mixture Likelihood Approach for Generalized Linear Models.” *Journal of Classification*, **12**(1), 21–55.
- Wehrens R, Buydens LM, Fraley C, Raftery AE (2004). “Model-Based Clustering for Image Segmentation and Large Datasets Via Sampling.” *Journal of Classification*, **21**(2), 231–253.

Affiliation:

Bettina Grün
Institut für Angewandte Statistik / IFAS
Johannes Kepler Universität Linz
Freistädter Straße 315
4040 Linz, Austria
E-mail: Bettina.Gruen@jku.at

Friedrich Leisch
Institut für Statistik
Ludwig-Maximilians-Universität München
Ludwigstraße 33
80539 München, Germany
E-mail: Friedrich.Leisch@stat.uni-muenchen.de
URL: <http://www.stat.uni-muenchen.de/~leisch/>